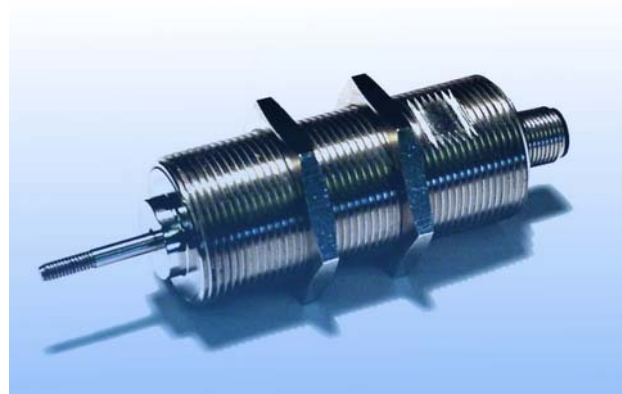


## Inductive Displacement Sensor

### Series **SM30**



- Thread M30x1.5
- Stroke up to 15mm
- Built in electronics
- Protection class IP66/67
- Accuracy 0,5% or 0,25%

#### Construction and operating principle:

A nickel iron core will be moved linear inside of a coil form. The displacement of the core leads to an inductance variation in both coils. The built in electronic circuit converts the variation into a signal proportional to the displacement.

#### Standard measuring stroke:

5 mm	10 mm	15 mm
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#### Technical data:

Accuracy	< 0,5% or 0,25%
Temperature drift	< 0,01% / °C
Measurement frequency	800 Hz
Temperature range	-20°C to +85°C
Resistance to shock	250g SRS 20-2000Hz
Resistance to vibration	20g rms (50g peak)
Protection class	IP66 *

\*with mounted mating plug

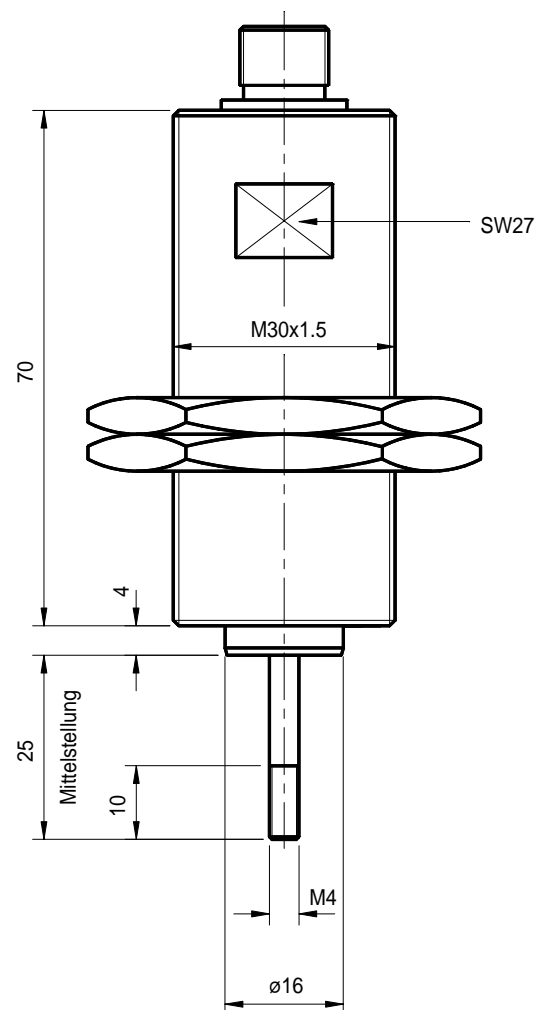
**Note:** Unless otherwise stated, all values are valid at +20°C ambient temperature and 30 VDC or ±15 VDC supply voltage, starting 10 minutes after switch-on.

#### Standard versions:

Type	Output	Supply voltage $U_B$ *	Signal**	Mid
SM301	0 .. 20 mA	20 .. 32 V	increasing	10 mA
SM302			decreasing	
SM303	4 .. 20 mA	20 .. 32 V	increasing	12 mA
SM304			decreasing	
SM305	± 10 V	±13 .. ±16 V	increasing	0 V
SM306			decreasing	
SM307	0..10 V	20 .. 32 V	increasing	5 V
SM308			decreasing	

\* Pole reversal protection

\*\* Increasing signal by moving the plunger in the direction towards the plug



**Current output (SM301..304):**

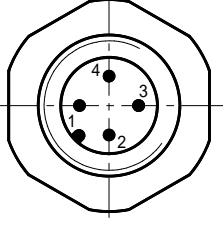
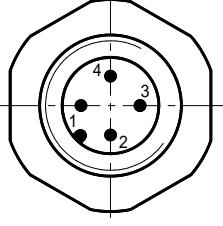
Output signal	0..20 mA or 4..20 mA
Supply current $I_B$	max. 60 mA
Load resistance $R_L$	0..500 $\Omega$
Residual ripple	< 0,005 mA <sub>SS</sub>
Dependence on $R_L$	< 0,001% for $\Delta R_L = 100\Omega$
Dependence on $U_B$	< 0,05% for $\Delta U_B = 1V$

**Voltage output (SM305..308):**

output signal	$\pm 10$ VDC or 0..10 VDC
Supply current $I_B$	max. 50 mA
Permissible load $R_L$	$\geq 2$ k $\Omega$ (short-circuit proof)
Residual ripple	< 5 mV <sub>SS</sub>
Residual voltage SM307/308	max. 0,1 VDC
Dependence on $U_B$	< 0,05% for $\Delta U_B = 1V$

**Electrical connections at plug**

(view to the plug at sensor)

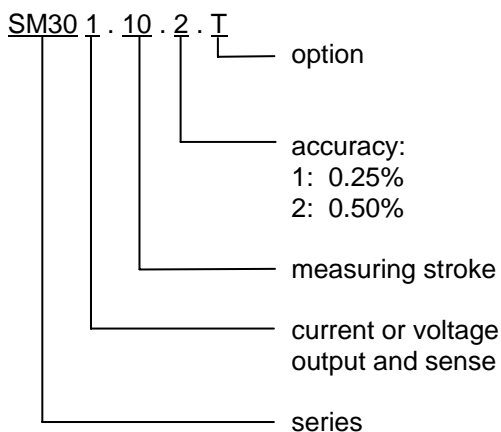
4-channel output /1 /2 /3 /4 /7 /8	4-channel output /5 /6
	
1: + $U_B$ 2: not connected 3: $I_A / U_A$ (output) 4: - $U_B$ (0V)	1: + $U_B$ 2: 0V 3: $U_A$ (output) 4: - $U_B$

**Materials:**

housing	nickel plated brass
plunger	stainless steel
core	stainless nickel-iron alloy
connector	nickel plated brass
contacts	gold plated brass

**Options and accessories:**

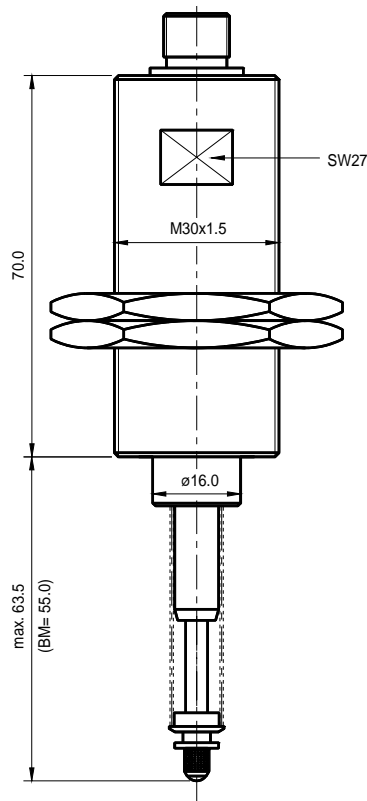
Version .T	gauge type
Version .B	with bellows

**Order code**

Order codes for customer specified versions will be named at plant.

**example: SM303.10.2**

Sensor series 30, output 4-20 mA (increasing), 10mm measuring stroke, accuracy 0,5%



Vertrieb durch



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